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A Robust Panel Unit Root Test in the Presence of Cross Sectional Dependence

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Problems arise in testing the stationarity of the panel in the presence of cross sectional dependence and outliers. The currently available panel unit root tests are very much affected by the presence of outliers. As such, this article introduces an alternative test which is robust to outliers and cross sectional dependence. The performance and robustness of the proposed test is discussed and comparisons are made to the existing tests via simulation studies.

Keywords: Cross sectional dependence, outliers, unit root, robust test, panel model.

Introduction

The investigation of the stationary in panel data has received great attention in panel analysis for the past few decades. It is an important issue in modeling the panel with the involvement of times series dimension in this study. This investigation can be done via unit root test. The panel unit root tests can be found in Im et al. (2003), Levin and Lin (1992, 1993), Levin et al. (2002), Bai and Ng (2004), Philips and Sul (2003), Moon and Perron (2004), Pesaran (2007) and Choi (2001, 2002). Hurlin (2010) distinguished two generations of unit root tests on which the first generation tests relied on the assumption that all cross sectional units are independent. The first generation of unit root tests were those proposed by Quah (1994), Breitung and Meyer (1994) and Levin and Lin (1992, 1993).

For the second generation of panel unit root tests, the presence of cross sectional dependence (hereafter CD) among the residuals is allowed within the panel. The assumption of CD is due to the evidence obtained on the strong comovements among the economic variables (Barbieri, 2009). The assumption that the individual time series in the panel are cross sectional independent is not practical in the context of cross country regressions. As argued by O'Connell,

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(1998), the presence of such CD may affect the finite sample behaviour of the panel unit root test which subsequently results to the incorrect decision in a unit root test. Those who proposed the tests which incorporated the CD were: Pesaran (2007), Philips and Sul (2003), Bai and Ng (2004), Moon and Perron (2004) and Choi (2002).

The existence of outliers implies that some shocks will only have temporary effects and thus, providing that they are sufficiently large or sufficiently frequent indicated that the series is stationary (Franses & Haldrup, 1994). Martin and Yohai (1986) showed via the simulation experiment that an additive outliers biases Ordinarily Least Squares (OLS) estimator downward for the parameter in a stationary first order autoregressive process. Hence, in some situations it could be expected that the additive outliers will establish the wrong impression that a time series is stationary when it is actually non-stationary. In addition, the presence of a cross sectional dependence may deteriorate the asymptotic distribution of the standard unit root test which is normally distributed (Philips & Sul, 2003; Banerjee, 1999). Due to such interest, a robust unit root test in the panel data model is proposed which aims at reducing the effects of outliers in the presence of the CD. Specifically, the presence of the unit root will be tested when both the CD and outliers exist in the panel. The finite sample behaviour of the proposed test is studied and its performance is evaluated through the Monte Carlo simulation study.

Model and Tests

Pesaran Unit Root Test

Specifically, in the presence of CD, the following model was considered by Pesaran (2007) to test the presence of the unit root:

$$\Delta y_{it} = \alpha_i + b_i y_{it-1} + \gamma_i f_t + \varepsilon_{it}; \quad i = 1, 2, ..., N. \quad t = 1, 2, ..., T$$
 (1)

where $\Delta y_{it} = y_{it} - y_{it-1}$; y_{it} is an i^{th} observation observed at a particular time t, α_i is the intercept, and b_i is a parameter for the variable of y_{it-1} . The presence of CD is represented by $\gamma_i f_t$ where f_t is the latent factor and γ_i is factor loadings that is common across cross sectional units i and \mathcal{E}_{it} is the random error. This model can be employed for a larger and complicated set of time series. In the absence of the unit root, negative values for b_i are expected. Specifically, the hypothesis test for a unit root is defined as follows:

$$H_0: b_i = 0;$$
 for all $i = 1, 2, ..., N$
 $H_1: b_i < 0;$ for some $i = 1, 2, ..., N$ (2)

Rejecting the null explains that the panel is stationary (no unit root). Model (1) can be expressed as cross sectional Augmented Dickey-Fuller (CADF) model:

$$\Delta y_{it} = \alpha_i + b_i y_{it-1} + c_i \overline{y}_{t-1} + d_i \Delta \overline{y}_t + e_{it}; \quad i = 1, 2, ..., N. \quad t = 1, 2, ..., T$$
(3)

where the standard of Augmented Dickey-Fuller (ADF) model is improved up to more variables in independent variables in model (3), that are; cross section averages of lagged levels (\overline{y}_{t-1}) and first differences of the individual series ($\Delta \overline{y}_t$), i in the model. Pesaran has shown that the effect of CD can be eliminated by using model (3). Thus, let CADF_i be the ADF statistics for the ith cross sectional unit given by the t-ratio of the OLS estimate \hat{b}_i of b_i in the CADF regression (3). Then, the Pesaran unit root test is given by

$$CIPS = \frac{\sum_{i=1}^{N} CADF_i}{N}$$
 (4)

where CIPS stands for cross sectional augmented IPS (Im et al. (1997) unit root test). This CADF_i is given by

$$CADF_{i} = t_{i}(N,T) = \frac{\left(\mathbf{y}_{i,-1}^{T} \overline{\mathbf{M}} \mathbf{y}_{i,-1}\right)^{-1} \left(\mathbf{y}_{i,-1}^{T} \overline{\mathbf{M}} \Delta \mathbf{y}_{i}\right)}{\sqrt{\sigma_{i}^{2} \left(\mathbf{y}_{i,-1}^{T} \overline{\mathbf{M}} \mathbf{y}_{i,-1}\right)^{-1}}}$$
(5)

where
$$\mathbf{y}_{i,-1} = (y_{i1}, \dots, y_{iT-1})^T$$
, $\Delta \mathbf{y}_i = (\Delta y_{i2}, \Delta y_{i3}, \dots, \Delta y_{iT})^T$; $\sigma_i^2 = \frac{\sum_{t=1}^T \hat{e}_u^2}{T-4}$, with $\hat{e}_{it} = \Delta y_{it} - \Delta \hat{y}_{it}$ and $\bar{\mathbf{M}}$ is defined as $\bar{\mathbf{M}} = \mathbf{I}_t - \bar{\mathbf{H}} (\bar{\mathbf{H}}^T \bar{\mathbf{H}})^{-1} \bar{\mathbf{H}}^T$ and $\bar{\mathbf{H}} = (\mathbf{I}, \Delta \bar{\mathbf{y}}_t, \bar{\mathbf{y}}_{t-1})$. \mathbf{I}_t is a unit matrix of order $T \times T$ and $\bar{\mathbf{H}}$ is the combination of the dummy variables, average of cross section of the first difference of y_{it} and its first lagged value y_{it-1} . The asymptotic distribution of this distribution is more skewed

compared to the ADF (asymptotically normal) distribution in the presence of CD (Philips and Sul, 2003). The critical value of the test statistics in (5) is given in Table 1 and those are obtained from the simulation experiment based on the CADF model.

Proposed Unit Root Test

The Pesaran's unit root test uses the OLS procedure that is non-robust. It has been known in the literature that the OLS is sensitive to the influence of outliers in the data. Hence, to limit the influence of outliers in the data in investigating the presence of the unit root in the model, the Generalized M-estimator is applied and it is obtained by solving the following equation:

$$\sum_{t=1}^{T} u_{i}(y_{it-1}) v_{i}(y_{it-1}) \psi_{i}\left(\frac{\hat{e}_{it}(b_{i})}{\hat{\sigma}_{i} v_{i}(y_{it-1})}\right) y_{it-1} = 0; \quad \text{for } i = 1, 2, ..., N$$
 (6)

where $u_i(y_{it-1})=1$ and $v_i(y_{it-1})=\frac{1}{d(y_{it-1})}$. The $d(y_{it-1})$ is given as a measure of

the outlying the y_{it-1} in the X-space from its mean value. Here, ψ_i (.) is the derivative of ρ_i (.), where ρ_i (.) is a differential convex function (with minimum at 0) and is known as the robustifying criterion function while $\hat{e}_{it}(b_i)$ is the estimated residuals and $\hat{\sigma}_i$ is the robust scale obtained from the first iteration of M-estimation.

To test for a unit root, a similar hypothesis statement as in (2) is considered. Under H_0 of no unit root, the generalization of the test is given by:

$$t_{i}^{*} = \frac{\hat{b}_{i}^{*} - b_{i}}{\sqrt{Var(\hat{b}_{i}^{*})}}$$
 (7)

where \hat{b}_{i}^{*} is the Generalized M-estimator where it is computed as follows:

$$\hat{b}_{i}^{*} = \left(\mathbf{y}_{i,-1}^{T} \mathbf{G}_{i} \mathbf{y}_{i,-1}\right)^{-1} \left(\mathbf{y}_{i,-1}^{T} \mathbf{G}_{i} \Delta \mathbf{y}_{i}\right)$$
(8)

where $\mathbf{y}_{i,-1} = (y_{i1}, \dots, y_{iT-1})^T$, $\Delta \mathbf{y}_i = (\Delta y_{i2}, \Delta y_{i3}, \dots, \Delta y_{iT})^T$ and $\mathbf{G}_i = \overline{\mathbf{M}}^* \mathbf{W}_i (z_{it})$ with $z_{it} = d_i (y_{it-1}) \frac{\hat{e}_{it} (b_i)}{\hat{\sigma}_i}$. The $Var(\hat{b}_i^*)$ is given by

$$Var(\hat{b}_{i}^{*}) = \left(\mathbf{y}_{i,-1}^{T} \mathbf{\bar{M}}^{*} \mathbf{y}_{i,-1}\right)^{-1} \hat{\sigma}_{i}^{2} \frac{E\left(\psi_{i}\left(\frac{\hat{e}_{it}\left(b_{i}\right)}{\hat{\sigma}_{i} v_{i}\left(y_{it-1}\right)}\right)\right)^{2}}{\left(E\left(\psi_{i}^{\prime}\left(\frac{\hat{e}_{it}\left(b_{i}\right)}{\hat{\sigma}_{i} v_{i}\left(y_{it-1}\right)}\right)\right)\right)^{2}}.$$

$$(9)$$

where $E(\psi_i(.))$ and $E(\psi_i(.))$ are the expected values of robustifying criterion function $\psi_i(.)$ and derivative of $\psi_i(.)$, respectively. The $\overline{\mathbf{M}}^*$ is computed as $\overline{\mathbf{M}}^* = \mathbf{I}_t - \overline{\mathbf{H}}^* (\overline{\mathbf{H}}^{*T} \overline{\mathbf{H}}^*)^{-1} \overline{\mathbf{H}}^{*T}$; \mathbf{I}_t is an identity T by T matrix and $\overline{\mathbf{H}}^* = (\mathbf{1}, \psi(\overline{y}_{t-1}), \psi(\Delta \overline{y}_t))$. The value of $\psi(.)$ in $\overline{\mathbf{H}}^*$ takes the form

$$\psi\left(\overline{y}_{t-1}\right) = \begin{cases}
\overline{y}_{t-1} & ,if |\overline{y}_{t-1}| \leq c \\
sign(\overline{y}_{t-1}) \times \left| \operatorname{median}\left(y_{1t-1}, \dots, y_{Nt-1}\right) \right| & ,elsewhere \\
and & ,if |\Delta \overline{y}_{t}| \leq d \\
\psi\left(\Delta \overline{y}_{t}\right) = \begin{cases}
\Delta \overline{y}_{t} & ,if |\Delta \overline{y}_{t}| \leq d \\
sign(\Delta \overline{y}_{t}) \times \left| \operatorname{median}\left(\Delta y_{1t}, \dots, \Delta y_{Nt}\right) \right| & ,elsewhere
\end{cases}$$
(10)

where c and d are the critical values and computed as $3\hat{\sigma}_{\overline{y}_{t-1}}$ and $3\hat{\sigma}_{\Delta\overline{y}_t}$, respectively. The $\hat{\sigma}_{\overline{y}_{t-1}}$ and $\hat{\sigma}_{\Delta\overline{y}_t}$ are robust scale with $\hat{\sigma}_{\overline{y}_{t-1}} = 1.4825$ median $\left|\overline{y}_{t-1} - \text{median}\left(\overline{y}_{t-1}\right)\right|$, $\hat{\sigma}_{\Delta\overline{y}_t} = 1.4825$ median $\left|\Delta\overline{y}_t - \text{median}\left(\Delta\overline{y}_t\right)\right|$, respectively. These robust scales are chosen to achieve specified level of efficiency and are called as the Median Absolute Deviation (MAD) with the tuning constant 1.4825 where $\hat{\sigma}_{\overline{y}_{t-1}}$ and $\hat{\sigma}_{\Delta\overline{y}_t}$ are consistent for σ at the normal distribution.

The proposed unit root test is the average of t_i^* which is given by

$$RCIPS = \overline{t}_{i}^{*} = \frac{\sum_{i=1}^{N} t_{i}^{*}}{N}$$
(11)

where t_{i}^{*} is given in (7).

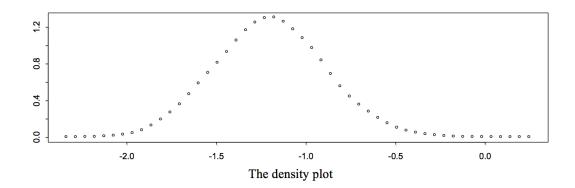
The asymptotic distribution of the test statistics given in (7) is obtained through the extensive simulation experiment. Based on Figure 1, the RCIPS unit root test tends to have an approximate t-distribution with a mean μ and a standard deviation, σ . As the sample size increase, it is believed that the RCIPS will approach to a standard normal distribution. This result is comparable with Pesaran (2007) under conditions where e_{it} is normally distributed.

To investigate the performance of the RCIPS, the critical region of test statistics is required. Therefore, the critical region of RCIPS test is obtained through simulation experiment at the 0.05 level of significance and it is given in Table 2. The data generating process (DGP) and results are given in the next section.

Finite Sample Behavior of the Tests

Following Pesaran (2007), the following DGP is considered: $y_{it} = \mu_i (1 - \varphi_i) + \varphi_i y_{it-1} + e_{it}$; $e_{it} = \gamma_i^T f_t + \varepsilon_{it}$; $\mu_i \sim iidN(0,1)$; $\varepsilon_{it} \sim iidN(0,\sigma_i^2)$; $\sigma_i^2 \sim iidU[0.5,1.5]$. The presence of CD is characterized by the latent factor $f_t \sim iidN(0,1)$ and strong CD, $\gamma_i \sim iidU(0.5,1.5)$. The performance of the tests is measured by setting: 1) $\varphi_i = 1$ and 2) $\varphi_i \sim U[0.75,0.95]$ for computing the size (incorrect detection) and power (correct detection) of the test, respectively.

A panel contaminated by outliers is represented by $y^*_{it} = y_{it} + \xi(L)\omega I_{it}(\tau)$ for i = 1, 2, ..., N. t = 1, 2, ..., T, where y^*_{it} is the observed contaminated series, y_{it} is the uncontaminated series, $\xi(L)$ is the dynamic pattern of the outliers, ω is the magnitude of outliers. $I_{it}(\tau)$ is the indicator function of the presence of outlier and will takes the value of 1 at time $t = \tau$ (chosen at random) and 0 elsewhere.



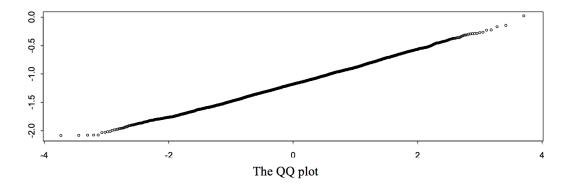


Figure 1. The Density and QQ plots of t-statistics (RCIPS unit root test)

*Note. Figure 1 provides results of the test statistic of the proposed unit root test (RCIPS) which is based on 5,000 runs for a sample size (N, T) = (200, 200). Based on this figure, the RCIPS tends to have a approximate t-distribution with mean μ and a standard deviation σ .

Two types of outliers are considered in this study; additive outliers (AO) and temporary change (TC). The AO only affect the level but leave the variance unaffected. The TC will produce an abrupt step and dies out gradually in time. Hence, in y_{it}^* , $\xi(L)=1$ in the presence of AO and TC takes the form of $\xi(L)=\frac{1}{1-\delta L}$ where δ represents the velocity of the dynamic effect and is bounded by [0, 1] (Tsay, 1998). The performance of the tests is investigated at the 5% level of significance using the sample sizes N=(20,30,50) and T=(20,30,50,100,200) with 1,000 replications.

Results and Discussion

The size and power of the unit root tests are investigated for the uncontaminated panel, the panel with AO and the panel with TC. These are tabulated in Tables 3 to 4 for the size and power of the tests, respectively. The results of the tests are reported by rows: 1) CIPS and 2) RCIPS with three columns of the number of cross sectional units, N = (20, 30, 50). For each column of N = (20, 30, 50), results of the size and power of the unit roots tests are reported when the panel is 1) uncontaminated, 2) contaminated with AO, and 3) contaminated with TC.

In the uncontaminated panel, the CIPS unit root test gives a smaller size for a small sample but attains a reasonable size as *T* increases whereas the RCIPS is slightly oversized even when *N* and *T* are large. In the presence of the AO and TC, the sizes for the CIPS test are all zeros for all sample sizes. The RCIPS has smaller size in the presence of AO but achieves a good size of the test in the presence of TC compared to CIPS. These results are comparable when the panel is free from the outliers effect (see column of "no cont" of Table 3).

In investigating the power of the test in the uncontaminated panel, the CIPS gives slightly lower correct detection (power) of a unit root for $T \le 50$. The probability of correctly detect the presence of unit root however increasing (good power) as T increases and the result is comparable to those obtained in Pesaran (2007). The RCIPS outperforms the CIPS even for small sample. In the presence of the AO and TC the panel, the powers for the CIPS test are poor when $T \le 50$. The power however increases for $T \ge 100$ with an increasing N. The powers for both tests are good as N increases in the presence of TC in the panel. The RCIPS provides a sensible power when $T \le 30$ in the presence of the AO but outperforms the CIPS in the presence of the TC. Based on these results, the RCIPS provides a good reasonable size (close to 0.05) and power (greater than 0.95) in the presence of the AO and TC relative to CIPS especially when N and T are small.

Conclusion

An alternative approach to Pesaran unit root test is proposed in order to investigate the stationarity of the data when outliers occur in the panel. The proposed test is robust to the effect of spurious observation in data. The finite sample behaviour of the tests is studied and compared via the Monte Carlo experiments. The results show that the proposed unit root test provide comparable size and power of the test in uncontaminated panel and yield better results than Pesaran unit root test in the presence of outliers in the panel especially for the small pair of sample size.

Table 1. Critical Values of CIPS

N		20			30			50	
Level of significance / T	1%	5%	10%	1%	5%	10%	1%	5%	10%
20	-2.40	-2.21	-2.10	-2.32	-2.15	-2.07	-2.25	-2.11	-2.03
30	-2.38	-2.20	-2.11	-2.30	-2.15	-2.07	-2.23	-2.11	-2.04
50	-2.36	-2.20	-2.11	-2.30	-2.16	-2.08	-2.23	-2.11	-2.05
100	-2.36	-2.20	-2.11	-2.30	-2.16	-2.08	-2.23	-2.12	-2.05
200	-2.36	-2.20	-2.11	-2.30	-2.16	-2.08	-2.23	-2.12	-2.05

These results are quoted from Pesaran (2007). The critical values are obtained from the estimates of $\Delta Y_{it} = \alpha_i + b_i Y_{it-1} + c_i \Delta \overline{Y}_t + d_i \overline{Y}_{t-1} + e_{it}$ with the test statistic is given by regression based on 10,000 runs. The test statistic is given by $\overline{t}_i = \sum_{i=1}^N t_i / N$ (the details of this expression can be referred in equation (5)) and the results of the test statistics are reported at 1%, 5% and 10% level of significance.

Table 2. Critical Values of RCIPS

N		20			30			50	
Level of significance / T	1%	5%	10%	1%	5%	10%	1%	5%	10%
20	-1.6240	-1.3834	-1.2711	-1.5179	-1.3423	-1.2458	-1.4291	-1.2888	-1.2124
30	-1.6565	-1.4592	-1.3637	-1.6139	-1.4300	-1.3319	-1.5264	-1.3843	-1.2931
50	-1.7569	-1.5555	-1.4484	-1.6979	-1.4987	-1.4138	-1.6126	-1.4483	-1.3692
100	-1.8267	-1.6090	-1.5238	-1.7662	-1.5894	-1.6866	-1.6866	-1.5242	-1.4575
200	-1.8983	-1.6946	-1.5992	-1.8397	-1.6613	-1.5646	-1.7706	-1.6182	-1.5319

Following the work of Im et al. (2003), the DGP computing critical values for RCIPS test is given by $y_{it} = y_{it-1} + e_{it}$, with $e_{it} \sim iidN(0,1)$; for i = 1, 2, ..., N. t = 1, 2, ..., T based on 5,000 runs. The test statistic is given by $\overline{t}_i^* = \sum_{i=1}^N t_i^* / N$ (the details of this expression can be referred in equation (11)) and the results of the test statistics are reported at 1%, 5% and 10% level of significance.

Table 3. The size of the unit root tests

CIPS

	no cont	АО	тс	no cont	AO	TC	no cont	AO	тс
T/N		20			30			50	
20	0.006	0.000	0.000	0.003	0.000	0.000	0.006	0.000	0.000
30	0.011	0.000	0.000	0.004	0.000	0.000	0.002	0.000	0.000
50	0.012	0.000	0.000	0.014	0.000	0.000	0.009	0.000	0.000
100	0.047	0.000	0.000	0.022	0.000	0.000	0.028	0.000	0.000
200	0.034	0.000	0.008	0.035	0.000	0.000	0.025	0.000	0.000

RCIPS

	no cont	АО	TC	no cont	АО	тс	no cont	АО	TC
T/N		20			30			50	
20	0.041	0.008	0.039	0.058	0.006	0.038	0.056	0.004	0.056
30	0.074	0.013	0.042	0.042	0.011	0.023	0.062	0.002	0.045
50	0.053	0.004	0.030	0.049	0.026	0.032	0.059	0.021	0.054
100	0.076	0.048	0.051	0.078	0.073	0.045	0.074	0.052	0.039
200	0.069	0.081	0.042	0.057	0.076	0.052	0.080	0.073	0.044

The values are the probability of rejecting the null of a unit root based on 1000 replications in uncontaminated panel (column no cont), contaminated with AO (column AO) and contaminated with TC (column TC). The size (probability of rejecting the null of a unit root when the unit root is present in the data) of the test is computed for $\varphi_i = 1$. The H₀ is rejected if the respective test statistics is greater than theirs critical values (tabulated in Tables 1 and 2) at 5% level of significance.

Table 4. The Power of the unit root tests

CIPS

	no cont	AO	TC	no cont	AO	тс	no cont	AO	TC
T/N		20			30			50	
20	0.002	0.000	0.000	0.022	0.000	0.000	0.018	0.000	0.000
30	0.207	0.000	0.000	0.241	0.000	0.000	0.283	0.000	0.001
50	0.862	0.011	0.026	0.952	0.005	0.023	0.999	0.007	0.022
100	1.000	0.918	0.836	1.000	0.282	0.955	1.000	0.355	0.977
200	1.000	0.981	1.000	1.000	0.993	1.000	1.000	1.000	1.000

RCIPS

	no cont	АО	TC	no cont	АО	TC	no cont	AO	TC
T/N		20			30			50	
20	0.793	0.422	0.788	0.912	0.481	0.833	0.952	0.683	0.961
30	0.920	0.617	0.865	0.964	0.755	0.965	0.981	0.804	0.980
50	0.994	0.834	0.968	1.000	0.922	0.988	1.000	0.986	1.000
100	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000
200	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000	1.000

The values are the probability of rejecting the null of a unit root based on 1000 replications in uncontaminated panel (column no cont), contaminated with AO (column AO) and contaminated with TC (column TC). The power (probability of correctly rejecting the null of a unit root when the unit root is absence in the data) of the test is computed for $\varphi_i \sim U$ [1.75, 0.95]. The H₀ is rejected if the respective test statistics is greater than theirs critical values (tabulated in Tables 1 and 2) at 5% level of significance.

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